

MODULE 1.13 | ICAM BASIC

Target group:	Future operators and programmers
Requirements:	<ul style="list-style-type: none"> ▪ Module 1.1 ▪ Welding knowlegde (advisable)
Objective:	<ul style="list-style-type: none"> ▪ Operating on igm robot systems ▪ Welding on igm robot systems
Languages:	<ul style="list-style-type: none"> ▪ German ▪ English
Training duration:	3 days
Training hours:	Weekdays (except Friday), 08:00 a.m. to 04:30 p.m.
Participants:	min. 3 persons, max. 5 persons (trainings for 1 person on demand)
Price:	<p>on demand</p> <p>incl.: documentation (electronic), hospitality and local transportation</p> <p>excl.: hotel, breakfast and dinner</p> <p>A hotel can be organised by igm, please contact us if required</p>

Training content

Introduction of the iCAM system (software, hardware, spare parts, versions)
How to program with iCAM and library (weaving, fillgroup, etc.)
Hardware (camera mounting, cabling, typical problems, camera mounting positions vs visible areas)
Correction, masking
How to create a new template (basic)
CAMCAL
K5/K6 camera functions (parameters programmed at a work step)
How to program with an iCAM (track mode, using the parameters from the work step)
Creation of snapshots